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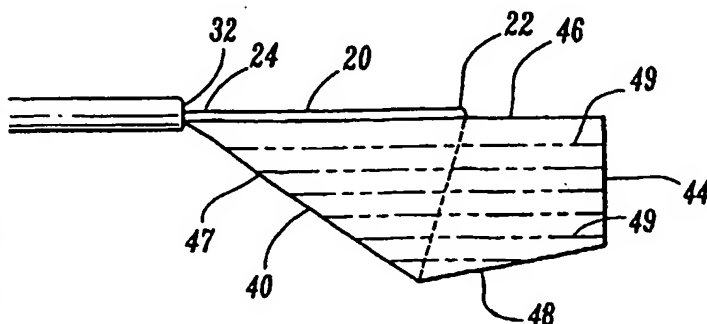
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(54) Title: **MINIMALLY INVASIVE REMOVAL DEVICE WITH BREAKAWAY SHEATH**



(57) Abstract: A tissue removal device is disclosed which includes an elongate shaft having a distal end and a proximal end, wherein the elongate shaft defines a longitudinal axis, a bag support defining an opening, the bag support being collapsible and expandable to open and close the opening, a bag operatively attached to the bag support, the bag having an open first end operatively secured to the bag support and a closed end, the first end being connected to the support so that when the bag support is in the collapsed position the bag opening is substantially closed, the bag having folds

including at least one transverse fold. The tissue removal device may further include a tube for receiving the shaft, bag support and bag.

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**MINIMALLY INVASIVE REMOVAL DEVICE  
WITH BREAKAWAY SHEATH**

**CROSS-REFERENCE TO RELATED APPLICATION**

The present application claims the benefit of and priority to U.S. Provisional  
10 Application Serial No. 60/368,191 filed on March 27, 2002, the entire contents of which are  
incorporated herein by reference.

**BACKGROUND**

1. Technical Field

15 The present disclosure relates to devices used for facilitating the removal of tissue  
portions during surgical procedures and, more particularly, to devices for removing tissue  
portions during minimally invasive surgical procedures. The present disclosure further relates  
to methods of collapsing the devices disclosed herein in order to reduce the cross-sectional  
profile thereof.

20

2. Background of Related Art

As a result of technological improvements in surgical instruments, surgical procedures  
using minimally invasive techniques can be performed causing less trauma to the patient. It is  
desirable to use smaller incisions so that a trocar or a cannula inserted into the incision is  
25 desirably smaller. Minimally invasive surgical procedures, however, have their limitations as  
the use of smaller diameter trocars require increasingly innovative and novel solutions for  
many traditional instrument applications such as tissue removal instruments. Tissue removal

instruments have tissue removal bags carried on deformable or inflatable frames which also define the opening of the bag. The inflatable frame instruments have openings that require an additional system for pressurization of the frame and/or bag which may also be a separately inflated member. Inflatable tissue removal instruments are vulnerable to accidental perforations and/or deflation, and are dependent upon the rigidity of the inflatable structure to support and contain the tissue as it is loaded into the bag and withdrawn through the trocar. It is desirable to decrease the cross-sectional area of the instrument for use with reduced diameter trocar systems.

A continuing need exists for an improved tissue removal system having a reduced cross-sectional diameter for passage through reduced diameter cannulas of trocar systems.

#### SUMMARY

According to one aspect of the present disclosure, a tissue removal device includes an elongate shaft having a distal end and a proximal end, wherein the elongate shaft defines a longitudinal axis, a bag support defining an opening, the bag support being collapsible and expandable to open and close the opening, a bag operatively attached to the bag support, the bag having an open first end operatively secured to the bag support and a closed end, the first end being connected to the support so that when the bag support is in the collapsed position the bag opening is substantially closed. The bag has folds including at least one transverse fold. It is contemplated that the tissue removal device further includes a tube for receiving the shaft, bag support and bag.

It is envisioned that the folds include folds approximately parallel with the longitudinal axis. It is further envisioned that a sheath is disposed about the bag assembly. Preferably, the sheath includes a weakness for breaking away from the bag. The sheath can

be fabricated from a flexible heat shrinking polymer. It is contemplated that the sheath is in the form of a mesh, a net and/or a lattice.

The tissue removal device further includes an actuation system operatively connected to the sheath in order to facilitate removal of the sheath from the bag assembly. It is  
5 envisioned that the actuation system includes a tear line formed in the sheath to facilitate tearing of the sheath. It is further envisioned that the actuation system includes a cord operatively connected to the tear line for facilitating the tearing of the sheath along the tear line. It is contemplated that the cord is connected to a control portion at the proximal end of the shaft.

10 It is envisioned that the actuation system includes an expandable member positioned within the bag assembly. Expansion of the expandable member is preferably initiated remotely from the bag.

It is further envisioned that the bag has a proximal edge and a distal edge and includes a slot formed in the vicinity of the bag support near the proximal edge to enable the diameter  
15 of the bag to be adjusted. In addition, the bag includes a control line for drawing the slot closed.

The bag can have any shape, including at least one of a conical and a trapezoidal shape. It is further contemplated that the tissue removal device includes a control portion operatively coupled to the proximal end of the shaft.

20 According to another aspect of the present disclosure, a method of collapsing a bag of a tissue removal device is disclosed. The method includes the steps of providing a minimally invasive tissue removal device including a shaft having a distal end and a proximal end and defining a longitudinal axis, a bag support, and a bag attached to the bag support, the bag having an upper end operatively coupled to the bag support and a lower end. The method

further includes the step of folding the bag transversely with respect to the longitudinal axis.

It is envisioned that the bag is folded onto itself such that the proximal edge crosses the distal edge.

- The method further includes the step of at least one of folding the bag so that the folds
- 5 are approximately parallel to the longitudinal axis. It is envisioned that the bag support has a collapsed position and an expanded position and further includes collapsing the upper end of the bag using the support. It is further envisioned that the bag is folded onto its self such that the proximal edge of the bag is substantially parallel with the longitudinal axis and/or such that the proximal terminal edge of the bag is substantially aligned with the longitudinal axis.
- 10 It is contemplated that the bag is folded so that a portion of the bag is disposed distally of a distal end of the support.

The method further includes the step of placing the folded bag and bag structure into a sheath. It is envisioned that the sheath includes a weakness and further includes the step of tearing the sheath at the weakness so as to release the bag.

- 15 According to a further aspect of the present disclosure, there is provided a minimally invasive tissue removal device for passage through a cannula, the device including an elongate shaft having a distal end portion and a proximal end portion, the elongate shaft defining a longitudinal axis, and a bag assembly operatively coupled to the distal end portion of the shaft. The bag assembly includes a bag support structure having a first position and a
- 20 second position, and a bag having an upper end and a lower end, the upper end having an open position and a closed position and being operatively secured to the bag support such that when the bag support is in the first position, the upper end of the bag is substantially open and when the bag support is in the second position, the upper end of the bag is substantially closed, the bag being folded over onto itself so as to form a transverse fold.

The tissue removal device further includes a removable sheath disposed about the bag assembly when in the bag is in the folded condition. It is envisioned that the bag has a proximal edge and a distal edge and wherein the bag is folded such that the proximal edge is substantially aligned with the longitudinal axis.

5        According to yet another aspect of the present disclosure, there is provided a minimally invasive tissue removal device for passage through a trocar, the device including an elongate shaft having a distal end portion and a proximal end portion, the elongate shaft defining a longitudinal axis, a bag support at the distal end of the shaft having a first position and a second position, the bag defining a plane when in the first position, and a bag having an  
10    open end and a closed end opposite the open end, the bag extending along a bag axis which is perpendicular to the longitudinal axis, the bag having an open position and a closed position, wherein the bag is folded over onto itself such that the bag axis is oriented substantially parallel to the longitudinal axis of the shaft.

It is envisioned that the bag is folded over onto itself, into a cylinder adjacent the bag  
15    support.

The presently disclosed endoscopic tissue removal device with breakaway sheath, together with attendant advantages, will be best understood by reference to the following detailed description in conjunction with the figures below.

## 20    **BRIEF DESCRIPTION OF THE DRAWINGS**

By way of example only, preferred embodiments of the present disclosure will be described herein with reference to the accompanying drawings, in which:

FIG. 1 is a cross-sectional view of a tissue removal device with a breakaway sheath in a folded position, in accordance with an embodiment of the present disclosure;

FIG. 2 is a top perspective view of the tissue removal device in accordance with the embodiment of FIG. 1 in an unfolded position;

FIG. 3 is a side elevational view of the tissue removal device of FIG. 1, in a method in accordance with a further embodiment;

5        FIG. 4 is a side elevational view of the tissue removal device of FIG. 3, at a later stage in the method;

FIG. 5 is a side elevational view of a tissue removal device in accordance with a further embodiment of the present disclosure;

10       FIG. 6 is a side elevational view of the tissue removal device in a method in accordance with a further embodiment;

FIG. 7 is a side elevational view of the tissue removal device of FIG. 6 at a later stage in the method;

FIG. 8 is a side elevational view of a tissue removal device in accordance with another embodiment of the present disclosure; and

15       FIG. 9 is a side view of a tissue removal device in accordance with the embodiment of FIG. 8 in a folded position.

#### **DETAILED DESCRIPTION OF PREFERRED EMBODIMENTS**

Preferred embodiments of the presently disclosed endoscopic tissue removal device  
20    will now be described in detail with reference to the drawing figures wherein like reference numerals identify similar or identical elements. In the drawings and in the description which follows, the term "proximal", as is traditional will refer to the end of the device which is closest to the operator, while the term "distal" will refer to the end of the device which is furthest from the operator.

Referring initially to FIGS. 1-4, one preferred embodiment of a tissue removal device in accordance with the present disclosure, is shown generally as 10. Device 10 includes a bag assembly 15, a shaft 30, a control system 60 and desirably includes a breakaway sheath 50. Shaft 30 defines a longitudinal axis "A". Bag assembly 15 includes a bag support structure or  
5 bag support 20 and a bag 40 operatively attached to bag support 20.

As seen in FIGS. 2-4, bag support 20 has a distal end portion 22 and a proximal end portion 24. Bag support 20 is deformable and is preferably biased to an open ring shape. The bag support 20 may comprise any openable structure. Bag support 20 may comprise one or more flexible resilient strips of metal or any other flexible and/or resilient materials. Bag  
10 support 20 is positioned within a plane A-B defined by axis "A" and a perpendicular axis "B". An axis "C" intersects and is perpendicular to axes "A and B". Bag support 20 is biased to the open position and is compressible to an elongate configuration wherein the dimension of the ring along minor axis "C" can approach zero, the sides of bag support 20 are close or in direct contact with one another. The specific geometric shape and size of bag support 20 or  
15 bag assembly 15 is dependent, however, upon the specific application of device 10. Thus, bag support 20 when in the open position can define any shape, such as a two dimensional geometric opening in the form of an ellipse, a triangle, or an oval, as well as three dimensional openings such as a scoop, for example.

Pouch or bag 40 is connected to bag support 20 and has a wall 45 defining a truncated  
20 conical shape. The bag may be connected to the bag support by a variety of known means such as the upper end of the bag being configured to receive the bag support. The bag 40 includes a flexible film or sheet and may be formed from a substantially transparent polymeric material. Polyurethane, latex or any other biocompatible material may be used. The bag may have any dimensions suitable for entrapping and/or removing tissue. A first end



42 of bag 40 defines opening 25 and a second end 44 provides a secured or closed end having sufficient strength to retain the tissue portions during the withdrawal of bag assembly 15 through reduced diameter trocars. Bag assembly 15 is desirably suitably configured for use in positioning, isolating, retaining and removing tissue portions during minimally invasive surgery.

Device 10 has a first position wherein bag assembly 15 is open such that bag 40 is unfolded and bag support 20 is uncompressed and defines an opening 25 for receiving tissue portions. In a second position, bag assembly 15 closed so that support 20 is compressed and bag 40 is tightly folded, rolled, and/or compressed. The use of the terms or phrase: folding of bag assembly 15, is intended to encompass at least the terms such as those identified above that are employed in the general process of folding bag 40 and may include collapsing the bag support 20. Folded bag assembly 15 becomes a sheathed bag assembly 51 in the second position when packaged in breakaway sheath 50. Sheathed bag assembly 51 has a reduced cross-sectional area perpendicular to the longitudinal axis or diameter for passing through a reduced diameter trocar. Reduced diameter trocars include trocars having inside diameters as small as 12 millimeters, and smaller. It is also envisioned that the present disclosure can attain additional reductions in the outside diameters of sheathed bag assembly 51. Preferably, when bag 40 is in the first position, bag 40 generally extends in the direction of axis "C".

Shaft or pusher 30 has a distal end portion 32 and a proximal end portion 34. Bag assembly 15 is operatively connected with distal end portion 32, such as, by connecting bag support 20 to distal end portion 32 of shaft 30. The shaft 30 is desirably formed from a polymeric material, but may be formed from any medical grade material. The shaft is slidably received in a tube, as discussed in U.S. Patent Nos. 5,647,372 and 5,465,731, the disclosures of which are entirely incorporated by reference herein. Control portion 60 (symbolically

shown) is connected to proximal end portion 34 for positioning, manipulating and orienting bag support 20 and bag 40 during surgery. Initially, bag assembly 15 is disposed within the tube and bag 40 is disposed on bag support 20 and contained in a sheath 50. Shaft 30 is used to position sheathed bag assembly 51 through the reduced diameter trocar and manipulate bag assembly 15 to the first or open position during minimally invasive surgery. The structure of shaft 30, operational deployment of bag assembly 15 and associated structure are described in commonly owned U.S. Patent No. 5,647,372 entitled "Specimen Retrieval Pouch and Method of Use" and U.S. Patent No. 5,465,731 entitled "Specimen Retrieval Pouch and Method of Use," both of which are incorporated entirely herein by reference. When shaft 30 is advanced through the tube using control portion 60, the control portion 60 is manipulated so that bag support 20 exits the tube. Shaft 30 can have a distal end 32 portion configured to bend or have a hinged connection, for example, which is manipulatable from control portion 60 and facilitates orientation of bag 30 after bag assembly 15 has been introduced into the body for receiving tissue portions and any other specimens therein.

Breakaway sheath 50 is configured and adapted to package and retain bag assembly 15 in the second closed position having a reduced dimension along the "C" axis. Preferably, breakaway sheath 50 is configured to breakaway or break apart from bag assembly 15. Breakaway sheath 50 preferably includes an easily manipulated release mechanism 55, in control portion 60, such that bag assembly 15, including bag 40 and bag support 20, can be easily released from sheath 50 by control portion 60. Once sheath 50 is broken away, the bias of bag support 20 and/or bag 40 causes bag assembly 15 to expand to the first position.

In one preferred embodiment, breakaway sheath 50 includes a flexible layer 52, which may include a medical grade plastic, such as for example, a single layer of film, or a single or a multilayer laminate. Layer 52 includes a weakness or perforations. Layer 52 has suitable

structural integrity for retaining bag 40 and bag support 20 in the folded and/or compressed position against any bias inherent in bag assembly 15 toward the second position. Layer 52 can have a uniform thickness, be continuous or discontinuous, provide a hermetic seal, or include reinforced portions in a geometric pattern, for example. Layer 52 could comprise a  
5 sheet, mesh, net, lattice or a combination thereof.

Layer 52 is wrapped around the folded bag 40 so that the folded bag 40 is disposed on bag support 20. Layer 52 is preferably configured as a shrink wrapped envelope, tube, or other layer shrunk and/or compressed around bag assembly 15 when folded in the second closed position. Layer 52 preferably closely conforms to and/or is tightly positioned around  
10 bag assembly 15. Sheath 50 can be fabricated from a suitable range of materials such that sheathed bag assembly 51 can be a flexible or rigid structure. Thus, it is envisioned that sheathed bag assembly 51 can be sufficiently flexible so as to be flexed into an arcuate shape from control portion 60.

In another alternative embodiment, breakaway sheath 50 can be a rigid or semi-rigid  
15 housing with or without perforations. This configuration can be employed to mechanically compress and secure bag assembly 15 in a fixed position. The housing can also be readily adaptable to vacuum packing. In operation, the housing could be easily opened using a remotely operated release mechanism 55 operated from control portion 60 to disconnect a pin or lever mechanism, for example. The housing can be withdrawn separately through the  
20 reduced diameter trocar after releasing bag assembly 15.

Alternatively, breakaway sheath 50 may be connected to bag assembly 15 such that when sheathed bag assembly 51 is released, sheath 50 remains at least partially connected to bag assembly 15. In this configuration, sheath 50 could be a series of bands or an extended flap connected to bag assembly 15, for example, such that bag assembly 15 can be secured in

the second closed position using the integral bag/sheath combination and could be held in the second closed position by an adjustable mechanical fastening device as well as by being shrink wrapped. Alternatively, sheath 50 can be connected to bag 40 by a cord or a ribbon (not shown). The cord would allow sheath 50 to be withdrawn with, but sequentially after, bag assembly 15, with tissue portions positioned therein, when sheath 50 is withdrawn through the reduced diameter trocar.

Breakaway sheath 50 may be fabricated from any suitable medical grade plastic or composite type material having the requisite strength and resistance to stretching. Preferably, the material is heat shrinkable. Alternate embodiments having rigid or semi-rigid enclosures as well as integral bag 40/sheath 50 systems may be fabricated from one or more suitable medical grade plastics, composites, or metals.

Release mechanism 55 is activated from control portion 60 by a surgeon. Release mechanism 55 preferably includes the weakness, or perforation, which may comprise an easily openable tear line 59 in layer 52 and an actuation system 56. Tear line 59 can be formed by one or more score lines, perforation lines, or edges that are continuous, but can be discontinuous. Actuation system 56 has components such as a suture, wire, pull tab, or cord 57 configured for connecting control portion 60 to tear line 59 and for facilitating the tearing of tear line 59 and the release of sheath 50. For example, a first end of cord 57 is connected to a distal end of sheath 50 and a second end of cord 57 is disposed at control portion 60 so that sheath 50 can be released by the drawing of one or more sutures 57 in a proximal direction to rupture sheath 50 along tear line 59 and release bag assembly 15. Any other mechanism for releasing sheath 50 may be used.

Actuation system 56 could also be at least partially positioned as a connecting mechanism for mating edges of sheath 50. For example, cord 57 positioned on opposing

edges of sheath 50 could also be a connecting mechanism linking portions of sheath 50 together in the second closed position. Cord 57 acting as the connecting mechanism could be released by a cutting or severing device configured to be pulled proximally against and severing cord 57 thereby releasing sheathed bag assembly 51. In the alternative, release  
5 mechanism 55 could be an integral part of layer 52, such as an elongated pull tab or cord 57, connected to a breakaway mechanical seam such as a zipper or similar mechanical snap or pressure seal configured for opening upon separation or drawing of the tab through the seam.

A further alternative remote actuation system 56 could include, for example, an  
10 expandable portion 58 strategically positioned within bag assembly 15 that could be expanded from control portion 60 to rupture tear line 59 of sheath 50. Expandable portion 58 could be a mechanical device such as a biasing member. Expandable portion 58 may comprise an expandable bladder in communication with an external source of fluid via control portion 60.

Breakaway sheath 50 can also be configured for an incremental release that allows the  
15 gradual expansion of sheathed bag assembly 51 from the second closed position to the first open position. For example, release mechanism 55 can include multiple sutures 57 connected with one or more tear lines 59 configured to accommodate a gradual and controlled expansion of bag assembly 15.

Referring now to FIGS. 3 and 4, a method of folding bag assembly 15 in accordance  
20 with an embodiment is depicted. Embodiments of the invention are particularly advantageous for a reduced diameter device for introduction during minimally invasive surgical procedures. Bag assembly 15 is positioned from the first open or unfolded position (as seen in FIG. 3) to the second closed or folded position (as seen in FIG. 1) by compressing bag support 20 such that it forms a narrow shape with opposed bends at the proximal end portion 24 and distal end

portion 22. The sides of bag support 20 can be in direct contact with or in close proximity to one another. The compressing of bag support 20 also compresses bag 40 into a flattened shape having a proximal folded edge 46 and a distal folded edge 48 such that opposing portions of wall 45 are in close to or in direct contact with one another. Bag 40 also extends  
5 away from bag support 20 to a bottom or second end 44. Bottom end 44 extends in a direction approximately parallel with axis "A".

Bottom or second end 44 of bag 40 is bent or folded over on itself such that proximal folded edge 46 is approximately aligned and in apposition with bag support 20 and bottom end 44 is disposed so that bottom end 44 extends in a direction parallel with axis "C", as best  
10 seen in FIG. 4. This folding step also forms a transverse fold 47 running at an angle relative to longitudinal axis "A". In certain embodiments, fold 47 is preferably approximately 45 degrees relative to longitudinal axis "A". Transverse fold 47 extends from edge 46 to edge 48. Preferably, transverse fold 47 begins at the junction of the proximal folded edge 46 with proximal end portion 24 and extends across bag 40 to distal folded edge 48. Bag 40 is then  
15 folded or rolled upward to be disposed parallel to longitudinal axis "A". Bag 40 may be folded along fold lines 49, for example, or the bag may be rolled, without creating any fold lines. This forms the final folded or second position of bag assembly 15 which is prepared for packaging with breakaway sheath 50, as described above. The folding of bag 40 in this manner has been found to produce a low profile folded bag, such that smaller diameter tubes  
20 can be used.

This folding or rolling process advantageously extends bag 40 along longitudinal axis "A" prior to the final folding step such that the folding of the material of bag 40 is extended over a greater distance along longitudinal axis "A". This enables bag 40 to be more tightly folded and/or rolled into a smaller diameter for packaging and passing through reduced

diameter trocars. In certain embodiments, the above process is capable of folding and sheathing bag assembly 15 into a configuration having an outside diameter sized for use with a trocar with an internal diameter of approximately 12 millimeters, or smaller.

It is readily envisioned that further reductions in diameter can be made to bag assembly 15. For example, the steps of the folding or rolling process can be augmented by aspirating bag 40 sufficiently or folding bag 40 in a vacuum to avoid entrapping air in bag 40 during the folding process. Furthermore, bag 40 may be folded over on itself more than once before bag 40 is folded or rolled upwardly toward bag support 20.

It is also envisioned that the shrink wrap process of sheath 50 can further compress or reduce the diameter of bag assembly 15. The shrink wrap process can also be configured to proceed sequentially along the longitudinal axis "A", any other suitable directional orientation, or combination of directions of bag assembly 15, for example, to advantageously force air from folded bag 40 to further reduce the volume of bag 40 before sheathing. In an alternative embodiment, bag 40 is vacuum packed or folded in a vacuum and shrink wrapped/sealed using flexible plastic layer 52.

The bag may have a wide variety of shapes. Referring now to FIGS. 5-7, reductions in the diameter of a folded bag assembly 15 can be achieved in another embodiment including a bag 140 having a conical shape. Bag 140 includes a wall 145 having a first end 142 and a second end 144. First end 142 defines an opening (not shown) while second end 144 defines a tip that is a closed end. End 144 points downwardly along axis "C".

A method of packaging or folding bag 140 in a configuration having a low profile, reduced diameter, or small dimension along axis "C", is also described herein. Bag 140 is positioned from the first open or unfolded position (as seen in FIG. 5) to the second closed or folded position (as seen in FIG. 7) by compressing bag support 20 such that it forms a narrow

shape with opposed proximally and distally positioned bends forming two arcuate sides at distal end 22 and proximal end 24, positioning the sides in contact or in close proximity to one another. The compressing of bag support 20 also compresses bag 140 into a flat triangular shape having a proximal folded edge 146 at the proximal end of bag 140 and a distal folded edge 148 at the distal end of the bag 140 such that opposing portions of wall 145 are close or in direct contact. Second end 144 of bag 140 extends away from bag support 20.

Bottom or second end 144 of bag 140 is repositioned or folded on top of itself such that proximal folded edge 146 is approximately aligned with or approximately parallel to bag support 20 and so that bottom end 44 is directed along axis "A". Depending upon the dimensions of the bag, bag 140, in the second position, includes second end 144 extending in a distal direction and positioned at least partially distal to edge 148, as shown in FIG. 6. This step also forms a transverse fold 147 starting at end 146 toward end 148, or preferably at the junction of the proximal end 146 with proximal end portion 24 and extending across bag 140 to the distal folded edge 148. Bag 140 is then folded or rolled upward to be disposed parallel to longitudinal axis "A" and may be folded along fold lines 149, for example. This forms the final folded reduced diameter position of bag assembly 15 prior to packaging of bag assembly 15 with breakaway sheath 50.

As shown in FIGS. 8 and 9, reductions in the diameter of bag assembly 15 in the second position can also be achieved by configuring bag 40 to be at least partially separable from bag supports 20, in the vicinity of bag support 20. Bag 40 is configured with a rim 21 that receives bag support 20. In the first position, the first end 42 of the bag is able to slide along bag support 20 in the at least partially folded position. First end 42 is desirably fixedly connected to bag support 20 at distal end 22 using an adhesive, for example. Bag 40 in this configuration can be suspended over bag support 20 or at least partially suspended from bag



support 20. In this configuration, bag 40 retains its generally conical shape including second end 44, but has a break or slot 43 in the vicinity of proximal folded edge 46 in the vicinity of proximal end portion 24 configured to enable bag 40 to adjust its diameter and slide around bag support 20 from proximal end 24 to distal end 22. The slot 43 is sized to enable bag 40 to receive bag support 20 when the bag support is in either the collapsed or expanded positions. Thus, first end 42 of bag 40 in the vicinity of fold 46 can at least partially separate and slide freely along the sides of bag support 20 for folding into the second position. This advantageously accommodates first end 42 being slid at least partially towards distal end 22 folding bag 40 into a low profile configuration. The second end 44 desirably extends distally from distal end 22 generally along longitudinal axis "A", to facilitate folding into a low profile configuration. Bag 40 can then be rolled or folded with minimal overlap with bag support 20.

After being passed through the trocar during minimally invasive surgery, first end 42 of bag 40 can be slid along bag support 20 toward proximal end 24, concurrent with or prior to the expansion of bag support 20, by a cord 57. The cord is desirably deployed at control portion 60. In the alternative, bag 40 could be biased to slide toward distal end 22 concurrent with the expansion of bag support 20 to the first position. The slot 43 is desirably closed after bag assembly 20 has expanded by further drawing control lines 57 proximally such that the sides of slot 43 are brought together and slot 43 is closed. In further embodiments, the bag opening 25 may be closed using cord 57 or a separate suture, cord or line.

Although the illustrative embodiments of the present disclosure have been described herein, it is to be understood that the disclosure is not limited to those precise embodiments, and that various other changes and modifications may be affected therein by one skilled in the art without departing from the scope or spirit of the disclosure. For example, in further

embodiments, a collapsible or flexible container other than a bag may be used. All such changes and modifications are intended to be included within the scope of the disclosure.

**IN THE CLAIMS**

What is claimed is:

1. A tissue removal device, comprising:

an elongate shaft having a distal end and a proximal end, wherein the elongate shaft

5 defines a longitudinal axis;

a bag support defining an opening, the bag support being collapsible and expandable to  
open and close the opening;

a bag operatively attached to the bag support, the bag having an open first end operatively  
secured to the bag support and a closed end, the first end being connected to the support so that  
10 when the bag support is in the collapsed position the bag opening is substantially closed; and  
the bag having folds including at least one transverse fold.

2. The tissue removal device of claim 1, further comprising a tube for receiving the  
shaft, bag support and bag.

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3. The tissue removal device of claim 1, wherein the folds include folds  
approximately parallel with the longitudinal axis.

4. The tissue removal device of claim 1, further including a sheath disposed about  
20 the bag assembly.

5. The tissue removal device of claim 4, wherein the sheath includes a weakness for breaking away from the bag.

6. The tissue removal device of claim 4, wherein the sheath is fabricated from a flexible heat shrinking polymer.

7. The tissue removal device of claim 6, wherein the sheath is in the form of at least one of a mesh, net and lattice.

8. The tissue removal device of claim 4, further comprising an actuation system operatively connected to the sheath in order to facilitate removal of the sheath from the bag assembly.

9. The tissue removal device of claim 4, wherein the actuation system includes a tear line formed in the sheath to facilitate tearing of the sheath.

10. The tissue removal device of claim 9, wherein the actuation system includes a cord operatively connected to the tear line for facilitating the tearing of the sheath along the tear line.

11. The tissue removal device of claim 10, wherein the cord is connected to a control portion at the proximal end of the shaft.

12. The tissue removal device of claim 9, wherein the actuation system includes an expandable member positioned within the bag assembly.

5 13. The tissue removal device of claim 12, wherein expansion of the expandable member is initiated remotely from the bag.

14. The tissue removal device of claim 1, wherein the bag has a proximal edge and a distal edge and includes a slot formed in the vicinity of the bag support near the proximal edge to  
10 enable the diameter of the bag to be adjusted.

15. The tissue removal device of claim 14, wherein the bag includes a control line for drawing the slot closed.

15 16. The tissue removal device of claim 1, wherein the bag is conical in shape.

17. The tissue removal device of claim 1, wherein the bag is trapezoidal in shape.

18. The tissue removal device of claim 1, further comprising a control portion  
20 operatively coupled to the proximal end of the shaft.

19. A method of collapsing a bag of a tissue removal device, the method comprising the steps of:

providing a minimally invasive tissue removal device including

a shaft having a distal end and a proximal end and defining a longitudinal axis;

5 a bag support; and

a bag attached to the bag support, the bag having an upper end operatively coupled to the bag support and a lower end, and

folding the bag transversely with respect to the longitudinal axis.

10 20. The method according to claim 19, wherein the bag is folded onto itself such that the proximal edge crosses the distal edge.

21. The method according to claim 19, further comprising folding the bag so that the folds are approximately parallel to the longitudinal axis.

15

22. The method according to claim 19, wherein the bag support has a collapsed position and an expanded position and further comprising closing the upper end of the bag using the support.

20

23. The method according to claim 22, wherein the bag is folded onto itself such that the proximal terminal edge of the bag is substantially parallel with the longitudinal axis.

24. The method according to claim 19, wherein the bag is folded onto itself such that the proximal terminal edge of the bag is substantially aligned with the longitudinal axis.

25. The method according to claim 20, wherein the bag is folded so that a portion of the bag is disposed distally of a distal end of the support.

26. The method according to claim 19, further comprising the step of placing the folded bag and bag structure into a sheath.

27. The method according to claim 26, wherein the sheath includes a weakness and further comprising tearing the sheath at the weakness so as to release the bag.

28. A minimally invasive tissue removal device for passage through a cannula, the device comprising:

an elongate shaft having a distal end portion and a proximal end portion, the elongate shaft defining a longitudinal axis;

a bag assembly operatively coupled to the distal end portion of the shaft, the bag assembly including:

a bag support structure having a first position and a second position; and

a bag having an upper end and a lower end, the upper end having an open position and a closed position and being operatively secured to the bag support such that when the bag support is in the first position, the upper end of the bag is substantially open and when the bag

support is in the second position, the upper end of the bag is substantially closed;

the bag being folded over onto itself so as to form a transverse fold.

29. The tissue removal device according to claim 27, further comprising a removable  
5 sheath disposed about the bag assembly when in the bag is in the folded condition.

30. The tissue removal device according to claim 29, wherein the bag has a proximal  
edge and a distal edge and wherein the bag is folded such that the proximal edge is substantially  
aligned with the longitudinal axis.

10

31. A minimally invasive tissue removal device for passage through a trocar, the  
device comprising:

an elongate shaft having a distal end portion and a proximal end portion, the elongate  
shaft defining a longitudinal axis;

15 a bag support at the distal end of the shaft having a first position and a second position,  
the bag defining a plane in the first position; and

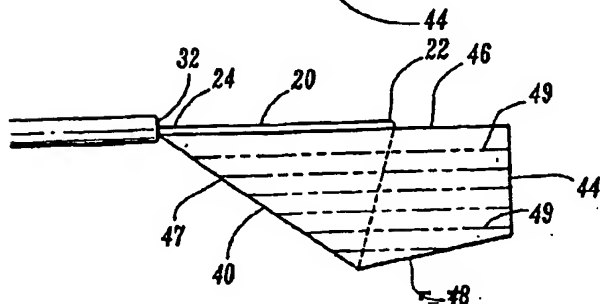
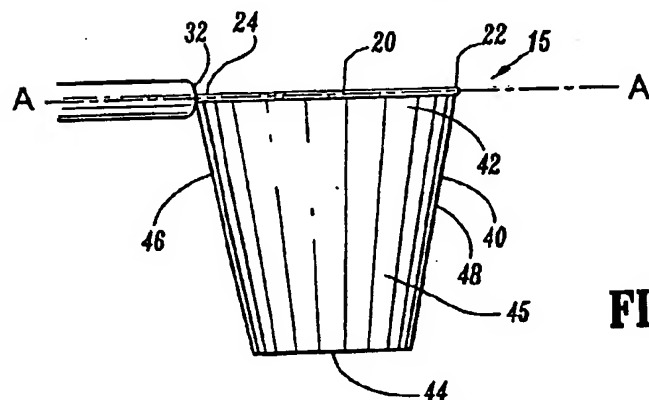
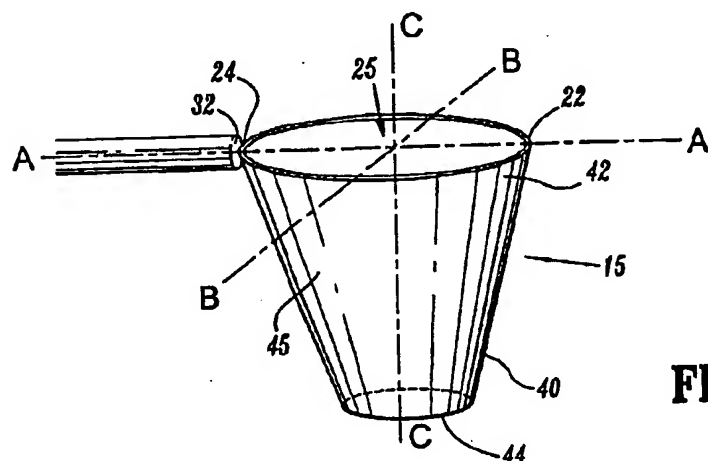
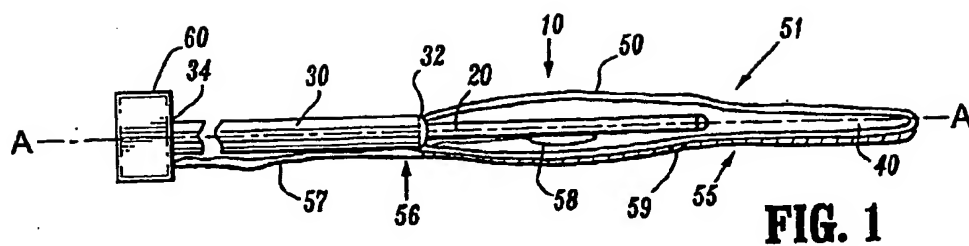
a bag having an open end and a closed end opposite the open end, the bag extending  
along a bag axis which is perpendicular to the longitudinal axis, the bag having an open position  
and a closed position;

20 wherein the bag is folded over onto itself such that the bag axis is oriented substantially  
parallel to the longitudinal axis of the shaft.

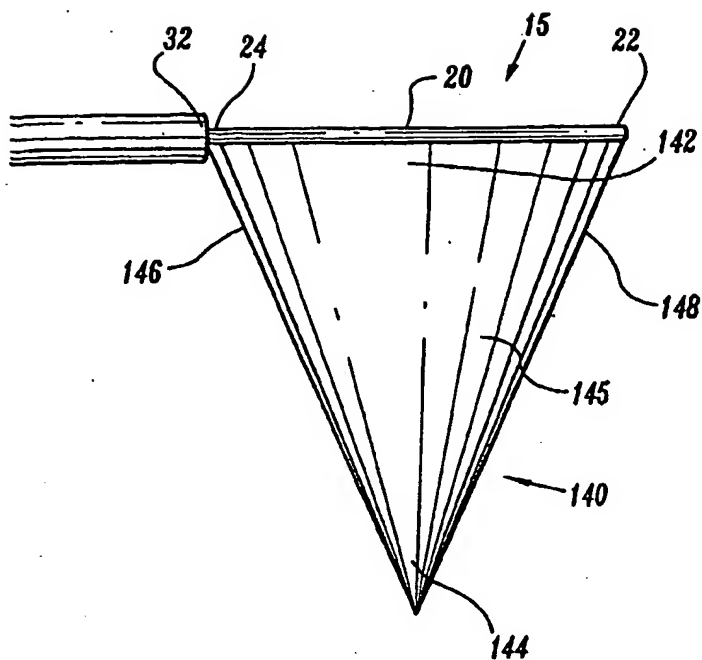


32. The tissue removal device of claim 31, wherein the bag is folded into a cylinder adjacent the bag support.

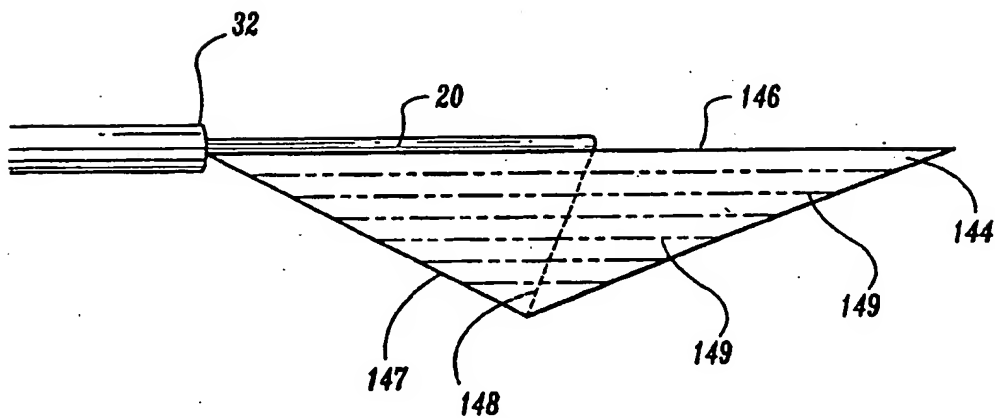
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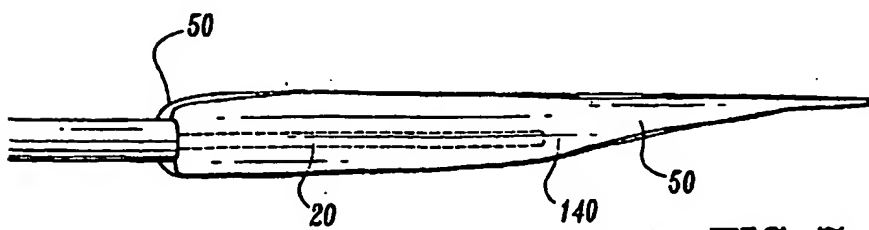
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**FIG. 5**

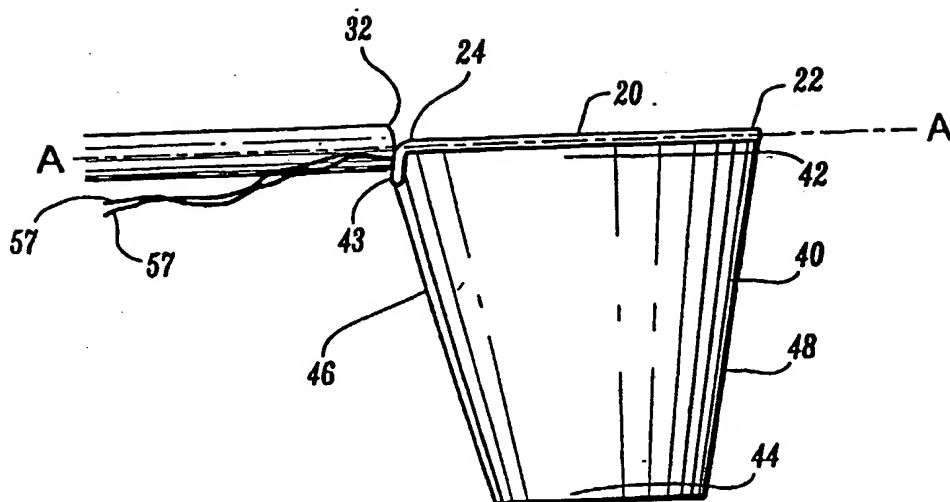


**FIG. 6**

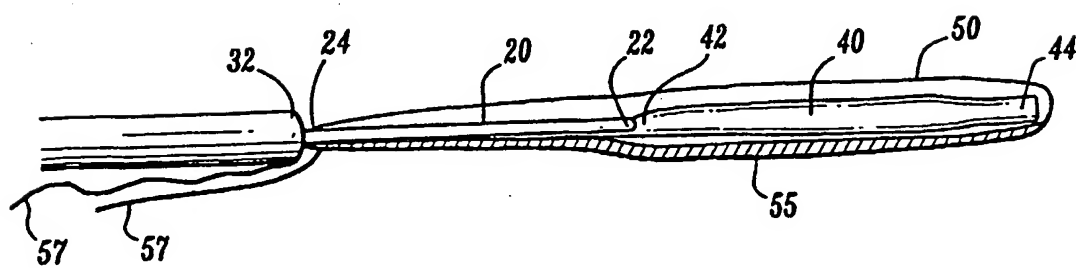


**FIG. 7**

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**FIG. 8**



**FIG. 9**

## INTERNATIONAL SEARCH REPORT

International Application No.

PCT/US 03/09133

## A. CLASSIFICATION OF SUBJECT MATTER

IPC 7 A61B17/00

According to International Patent Classification (IPC) or to both national classification and IPC

## B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

IPC 7 A61B

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)

EPO-Internal

## C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category *	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
Y	US 5 647 372 A (TOVEY H JONATHAN ET AL) 15 July 1997 (1997-07-15) cited in the application column 7, line 40 - line 57; figures 1A,2	1-3, 16, 19-25, 30, 31
Y	DE 196 24 826 A (RUESCH WILLY AG) 8 January 1998 (1998-01-08)  column 10, line 51 - column 11, line 15; figures 2,3	1-3, 16, 19-25, 30, 31
A	US 2001/002437 A1 (PAGEDAS ANTHONY C) 31 May 2001 (2001-05-31) the whole document	1, 2, 4, 19, 28, 31
A	US 5 341 815 A (COFONE MARK A ET AL) 30 August 1994 (1994-08-30) abstract; figures 1-5, 11	1, 2, 19, 28, 31



Further documents are listed in the continuation of box C.



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Date of the actual completion of the international search

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